# Geometric Theorem Proving

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## Geometric Automated Theorem Proving

An history more than sixty years long [CG01, Wan96]. Two major lines of research in GATP:

- Synthetic methods;
- Algebraic methods.

Mechanical Geometric Formula Derivation:

- Finding locus equation;
- Deriving geometry formulas.

News fields

- Geometric Tools: DGS/GATP/CAS/RGP/eLearning
- Formalisation.



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# AI (synthetic) Methods

Synthetic methods attempt to automate traditional geometry proof methods that produce human-readable proofs.

In 1950s Gelernter created a theorem prover that could find solutions to a number of problems taken from high-school textbooks in plane geometry [Gel59].

It was based on the human simulation approach and has been considered a landmark in the AI area for this time.

In spite of the success and significant improvements [BdC95, CP79, CP86, Gil70, KA90, Nev74, Qua89] with these methods, the results did not lead to the development of a powerful geometry theorem prover.

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Algebraic Methods: are based on reducing geometry properties to algebraic properties expressed in terms of Cartesian coordinates.

The biggest successes in automated theorem proving in geometry were achieved (i.e., the most complex theorems were proved) by algebraic provers based on:

- Wu's method [Cho87];
- ► Gröbner bases method [Buc06, BCJ<sup>+</sup>06, Kap86].

Decision procedures.

No readable, traditional geometry proofs, only a yes/no answer (with a corresponding algebraic argument).



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## Coordinate-free Methods

Instead of coordinates, three basic geometric quantities: the ratio of parallel line segments, the signed area, and the Pythagorean difference.

- Area method [CGZ93, JNQ11, QJ06a];
- Full angle method [CGZ94, CGZ96a];
- Solid geometry [CGZ95].

Geometric proofs, small and human-readable.

But:

- not the "normal" high-school geometric reasoning;
- for many conjectures these methods still deal with extremely complex expressions involving certain geometric quantities.



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- An approach based on a deductive database and forward chaining works over a suitably selected set of higher-order lemmas and can prove complex geometry theorems, but still has a smaller scope than algebraic provers [CGZ94, CGZ00].
- Quaife used a resolution theorem prover to prove theorems in Tarski's geometry [Qua89].
- A GATP based on coherent-logic capable of producing both readable and formal proofs of geometric conjectures of certain sort [SPJ10].
- Probabilistic verification of elementary geometry statements [CFGG97, RGK99].
- Visual Reasoning/Proofs [Kim89, YCG10a, YCG10b].



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# Mechanical Geometric Formula Derivation

 Locus Generation: to determine the implicit equation of a locus set [BAE07, BA12].

The set of points determined by the different positions of a point, the tracer, as a second point in which the tracer depends on, called the mover, runs along the one dimensional object to which it is restrained.

 Deriving Geometry Formulas: automatic derivation of geometry formulas [cCsG90, KSY94, RV99].

Example: find the formula for the area of a triangle *ABC* in terms of its three sides.



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# Geometric Tools & Integration Issues

Geometric tools: DGS & GATP & CAS & RGP.

 DGS - Dynamic Geometry Software [Gro11, Hoh02, Jac01, Jan06, RGK99] - "visual proofs" [CGY04];

► GATP - Geometry Automated Theorem Provers

- verification of the soundness of a geometric construction [JQ07].
- reason about a given DGS construction [CGZ96b, JQ06, Nar07a, QP06, QJ06b]
- ▶ human-readable proofs [JNQ11, QJ06a, QJ09].
- ▶ RGP Repositories of Geometric Problems [QJ07, Qua11].
- eLearning [ABY86, HLY86, QJ06b, SQ08, SQ10, SQ12]

Integration: Intergeo Project [SHK<sup>+</sup>10] — Deducation STREP Proposal [WSA<sup>+</sup>12].



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# Formalisation

Full formal proofs mechanically verified by generic theorem proof assistants (e.g. Isabelle [Pau94, PN90], Coq [Tea09]).

- Hilbert's Grundlagen [Hil77, MF03, DDS00];
- Jan von Plato's constructive geometry [Kah95, vP95];
- French high school geometry [Gui04];
- Tarski's geometry [Nar07b];
- An axiom system for compass and ruler geometry [Dup10];
- Projective geometry [MNS09, MNS10];
- Area Method [JNQ11, Nar06];
- Algebraic methods in geometry [MPPJ12].



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# Synthetic Methods

AI, intelligence simulated by a machine.

Al in Geometry, development of human-readable proofs.

- Geometric reasoning small and easy to understand proofs.
- Use of predicates only allow reaching fix-points.
- Some successes over the algebraic provers.

Seminal paper of Gelernter et al [Gel59].

- numerical model;
- constructing auxiliary points;
- generating geometric lemmas.

The AI approaches are not decision procedures and are less powerful then the algebraic approaches.



# Gelernter's GATP

Backward chaining approach.

$$\forall$$
geometric elements $[(H_1 \land \cdots \land H_r) \Rightarrow G]$ 

To prove G we search the *axiom rule set* to find a rule of the following form

$$[(G_1 \wedge \cdots \wedge G_r) \Rightarrow G]$$

until the sub-goals is one of the hypothesis.

The proof search will generate an and-or-proof-tree.



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Introduction Geometry Automated Theorem Provers Mechanical Geometric Formula Derivation New Directions Bibliography

### AI Methods



 $points(A, B, C) \land AB \| CD \land AD \| BC \land coll(E, A, C) \land coll(E, B, D) \Rightarrow AE = EC$ 



# GATPs - Synthetic methods

Two uses of the geometric diagram as a model [CP86]:

- the diagram as a filter (a counter-example);
- the diagram as a guide (an example suggesting eventual conclusions).

Top-down or bottom-up directions? A general prover should be able to mix both directions of execution [CP86].

The introduction of new points can be envisaged as a means to make explicit more information in the model [CP86].

Although various strategies and heuristics were subsequently adopted and implement, the problem of search space explosion still remains and makes the methods of this type highly inefficient [CP79, CP86].



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# Geometry Deductive Database

- In the general setting: structured deductive database and the data-based search strategy to improve the search efficiency.
- Selection of a good set of rules; adding auxiliary points and constructing numerical diagrams as models automatically.

The result program can be used to find fix-points for a geometric configuration, i.e. the program can find all the properties of the configuration that can be deduced using a fixed set of geometric rules.

Generate ndg conditions.

Structured deductive database reduce the size of the database in some cases by one thousand times.



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Geometry Deductive Database - The Orthocenter Theorem

 $points(A, B, C) \land coll(E, A, C) \land perp(B, E, A, C) \land coll(F, B, C) \land perp(A, F, B, C) \land coll(H, A, F) \land coll(H, B, E) \land coll(G, A, B) \land coll(G, C, H)$ 



The fix-point contains two of the most often encountered properties of this configuration:

- ▶ perp(C, G, A, B);
- $\blacktriangleright \angle FGC = \angle CGE$



# Quaife's GATP

Tarski axiomatic system: is, or rather its algebraic equivalent, complete and decidable.

Quaife developed a GATP for Euclidean plane geometry within the automated reasoning system OTTER (a resolution theorem prover) [Qua89].

(A1) Reflexivity axiom for equidistance.

$$\rightarrow u \cdot v \equiv v \cdot u$$

(A2) Transitivity axiom for equidistance.

$$u \cdot v \equiv w \cdot x, u \cdot v \equiv y \cdot z \to w \cdot x \equiv y \cdot z$$

(A4) Segment construction axiom, two clauses.

$$\begin{array}{l} (A4.1) \rightarrow B(u,v,\textit{Ext}(u,v,w,x)) \\ (A4.2) \rightarrow v \cdot \textit{Ext}(u,v,w,x) \equiv w \cdot x \end{array}$$

(...)



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# Quaife's GATP

### Heuristics

- maximum weight for retained clauses at 25,
- first attempt to obtain a proof in which no variables are allowed in any generated and retained clause.

The provers based upon Wu's algorithm, are able to prove quite more difficult theorems in geometry those by Quaife's GATP.

However Wu's method only works with hypotheses and theorems that can be expressed as equations, and not with inequalities as correspond to the relation B in Quaife's resolution prover.



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# Visual Reasoning/Representation

Visual Reasoning extend the use of diagrams with a method that allows the diagrams to be perceived and to be manipulated in a creative manner [Kim89].

Visually Dynamic Presentation of Proofs linking the proof done by a synthetic method (full-angle) with a visual presentation of the proof [YCG10a, YCG10b].



# Wu's Method

An elementary version of Wu's method is simple: Geometric theorem T transcribed as polynomial equations and inequations of the form:

• H: 
$$h_l = O, \dots, h_s = O, d_1 \neq 0, \dots, d_t \neq 0;$$
  
• C: c=0.

Proving T is equivalent to deciding whether the formula

$$\forall_{x_l,\ldots x_n} [h_1 = 0 \land \cdots \land h_s \land d_1 \neq 0 \land \ldots \land d_t \neq 0 \Rightarrow c = 0] \quad (1)$$

is valid.

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# Wu's Method

Computes a characteristic set C of  $\{h_1, \ldots, h_s\}$  and the pseudo-remainder r of c with respect to C.

If r is identically equal to 0, then T is proved to be true.

The subsidiary condition  $J \neq 0$ , where J is the product of initials of the polynomials in C are the ndg conditions [WT86, Wu00].

This is a decision procedure.


# Area Method — Basic Geometric Quantities<sup>1</sup>

#### Definition (Ratio of directed parallel segments)

For four collinear points *P*, *Q*, *A*, and *B*, such that  $A \neq B$ , the ratio of directed parallel segments, denoted  $\frac{\overline{PQ}}{\overline{AB}}$  is a real number.

#### Definition (Signed Area)

The signed area of triangle ABC, denoted  $S_{ABC}$ , is the area of the triangle with a sign depending on its orientation in the plane.

#### Definition (Pythagoras difference)

For three points A, B, and C, the Pythagoras difference, is defined in the following way:  $\mathcal{P}_{ABC} = \overline{AB}^2 + \overline{CB}^2 - \overline{AC}^2$ .

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### Properties of the Ratio of Directed Parallel Segments

• 
$$\frac{\overline{PQ}}{\overline{AB}} = -\frac{\overline{QP}}{\overline{AB}} = \frac{\overline{QP}}{\overline{BA}} = -\frac{\overline{PQ}}{\overline{BA}};$$
  
•  $\frac{\overline{PQ}}{\overline{AB}} = 0$  iff  $P = Q;$ 

EL1 (The Co-side Theorem) Let M be the intersection of two non-parallel lines AB and PQ and  $Q \neq M$ . Then it holds that  $\frac{\overline{PM}}{\overline{QM}} = \frac{S_{PAB}}{S_{QAB}}; \frac{\overline{PM}}{\overline{PQ}} = \frac{S_{PAQB}}{S_{PAQB}}; \frac{\overline{QM}}{\overline{PQ}} = \frac{S_{QAB}}{S_{PAQB}}.$ 



#### Properties of the Signed Area

$$\bullet \ \mathcal{S}_{ABC} = \mathcal{S}_{CAB} = \mathcal{S}_{BCA} = -\mathcal{S}_{ACB} = -\mathcal{S}_{BAC} = -\mathcal{S}_{CBA}.$$

- $S_{ABC} = 0$  iff A, B, and C are collinear.
- ▶  $PQ \parallel AB$  iff  $S_{PAB} = S_{QAB}$ , i.e., iff  $S_{PAQB} = 0$ .
- Let *ABCD* be a parallelogram, *P* and *Q* be two arbitrary points. Then it holds that  $S_{APQ} + S_{CPQ} = S_{BPQ} + S_{DPQ}$  or  $S_{PAQB} = S_{PDQC}$ .
- ► Let *R* be a point on the line *PQ*. Then for any two points *A* and *B* it holds that  $S_{RAB} = \frac{\overline{PR}}{\overline{PO}}S_{QAB} + \frac{\overline{RQ}}{\overline{PO}}S_{PAB}$ .



# Properties of the Pythagoras Difference

- $\mathcal{P}_{AAB} = 0.$
- $\mathcal{P}_{ABC} = \mathcal{P}_{CBA}$ .
- If A, B, and C are collinear then,  $\mathcal{P}_{ABC} = 2\overline{BA} \ \overline{BC}$ .

• 
$$AB \perp BC$$
 iff  $\mathcal{P}_{ABC} = 0$ .

▶ Let *AB* and *PQ* be two non-perpendicular lines, and *Y* be the intersection of line *PQ* and the line passing through *A* and perpendicular to *AB*. Then, it holds that

$$\frac{\overline{PY}}{\overline{QY}} = \frac{\mathcal{P}_{PAB}}{\mathcal{P}_{QAB}}, \quad \frac{\overline{PY}}{\overline{PQ}} = \frac{\mathcal{P}_{PAB}}{\mathcal{P}_{PAQB}}, \quad \frac{\overline{QY}}{\overline{PQ}} = \frac{\mathcal{P}_{QAB}}{\mathcal{P}_{PAQB}}.$$
...)



# The Area Method — The Proof Algorithm

# Express the hypothesis of a theorem using a set of constructive statements.

Each constructive statement introduces a new point.



The conclusion is expressed by a polynomial in some geometry quantities (defined above), without any relation to a given system of coordinates.

The proof is then developed by eliminating, in reverse order, the point introduced before, using for that purpose a set of lemmas.



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### Constructive Geometric Statements

- ECS1 construction of an arbitrary point U; (...).
- ECS2 construction of a point Y such that it is the intersection of two lines (LINE U V) and (LINE P Q); ndg-condition:  $UV \not\parallel PQ$ ;  $U \neq V$ ;  $P \neq Q$ . degree of freedom for Y: 0
- ECS3 construction of a point Y such that it is a foot from a given point P to (LINE U V); (...).
- ECS4 construction of a point Y on the line passing through point W and parallel to (LINE U V), such that  $\overline{WY} = r\overline{UV}$ , (...).
- ECS5 construction of a point Y on the line passing through point U and perpendicular to (LINE U V), such that  $r = \frac{4S_{UVY}}{P_{UVU}}$ , (...)

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#### Forms of Expressing the Conclusion

property	in terms of geometric quantities
points A and B are identical	$\mathcal{P}_{ABA} = 0$
points A, B, C are collinear	$\mathcal{S}_{ABC}=0$
AB is perpendicular to CD	$\mathcal{P}_{ABA}  eq 0 \land \mathcal{P}_{CDC}  eq 0 \land \mathcal{P}_{ACD} = \mathcal{P}_{BCD}$
AB is parallel to CD	$\mathcal{P}_{ABA}  eq 0 \land \mathcal{P}_{CDC}  eq 0 \land \mathcal{S}_{ACD} = \mathcal{S}_{BCD}$
O is the midpoint of AB	$\mathcal{S}_{ABO} = 0 \wedge \mathcal{P}_{ABA}  eq 0 \wedge rac{\overline{AO}}{\overline{AB}} = rac{1}{2}$
AB has the same length as CD	$\mathcal{P}_{ABA} = \mathcal{P}_{CDC}$
points A, B, C, D are har-	$\mathcal{S}_{ABC} = 0 \land \mathcal{S}_{ABD} = 0 \land \mathcal{P}_{BCB}  eq 0 \land \mathcal{P}_{BDB}  eq$
monic	$0 \land \frac{\overline{AC}}{\overline{CR}} = \frac{\overline{DA}}{\overline{DR}}$
angle ABC has the same mea-	$\mathcal{P}_{ABA} \neq 0 \land \mathcal{P}_{ACA} \neq 0 \land \mathcal{P}_{BCB} \neq$
sure as <i>DEF</i>	$0 \land \mathcal{P}_{DED} \neq 0 \land \mathcal{P}_{DFD} \neq 0 \land$
	$\mathcal{P}_{EFE} \neq 0 \land \mathcal{S}_{ABC} \cdot \mathcal{P}_{DEF} = \mathcal{S}_{DEF} \cdot \mathcal{P}_{ABC}$
A and $B$ belong to the same	$S_{ACD} \neq 0 \land S_{BCD} \neq 0 \land S_{CAD} \cdot \mathcal{P}_{CBD} =$
circle arc <i>CD</i>	$S_{CBD} \cdot \mathcal{P}_{CAD}$

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#### **Elimination Lemmas**

EL2 Let G(Y) be a linear geometric quantity and point Y is introduced by the construction (PRATIO Y W (LINE U V) r). Then it holds

$$G(Y) = G(W) + r(G(V) - G(U)).$$

EL3 Let G(Y) be a linear geometric quantity and point Y is introduced by the construction (INTER Y (LINE U V) (LINE P Q). Then it holds

$$G(Y) = \frac{S_{UPQ}G(V) - S_{VPQ}G(U)}{S_{UPVQ}}.$$
(...)

#### Constructive Steps & Elimination Lemmas

		Geometric Quantities				
		$\mathcal{P}_{AYB}$	$\mathcal{P}_{ABY}$ $\mathcal{P}_{ABCY}$	$S_{ABY}$ $S_{ABCY}$	$\frac{\overline{AY}}{\overline{CD}}$	$\frac{\overline{AY}}{\overline{BY}}$
ructive eps	ECS2	EL5	EL	EL11	EL1	
	ECS3	EL6	EL4		EL12	
St	ECS4	EL7	EL2		EL	13
Ŭ	ECS5	EL10	EL9 EL8		EL14	
		Elimination Lemmas				



# The Algorithm

- $\rightarrow S = (C_1, C_2, \dots, C_m, (E, F))$  is a statement in **C**.
- $\leftarrow \text{ The algorithm tells whether } S \text{ is true, or not, and if it is true,} produces a proof for S.$

Adding to that it is needed to check the ndg condition of a construction (three possible forms).



# An Example (Ceva's Theorem)

Let  $\triangle ABC$  be a triangle and *P* be an arbitrary point in the plane. Let *D* be the intersection of *AP* and *BC*, *E* be the intersection of *BP* and *AC*, and *F* the intersection of *CP* and *AB*. Then:



### Example — Proof

The proof of a conjecture is based on eliminating all the constructed points, in reverse order, until an equality in only the free points is reached.

$\frac{\overline{AF}}{\overline{FB}}  \frac{\overline{BD}}{\overline{DC}}  \frac{\overline{CE}}{\overline{EA}}$		

Elimination Steps: 3; Geometric Steps: 6; Algebraic Steps: 23; Total Steps: 32; CPU Time 0.004s. The GATP also provide the ndg conditions.



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 the point *F* is eliminated  
$$= \frac{S_{APC}}{S_{BCP}} \frac{S_{BPA}}{S_{CAP}} \frac{\overline{CE}}{\overline{EA}}$$
 the point *D* is eliminated  
$$= \frac{S_{APC}}{S_{BCP}} \frac{S_{BPA}}{S_{CAP}} \frac{S_{CPB}}{S_{ABP}}$$
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#### Area Method - Formalisation

#### Formalisation [JNQ11, Nar06, Nar09];

- 1.  $\overline{AB} = 0$  if and only if the points A and B are identical
- 2.  $S_{ABC} = S_{CAB}$
- 3.  $S_{ABC} = -S_{BAC}$
- 4. If  $S_{ABC} = 0$  then  $\overline{AB} + \overline{BC} = \overline{AC}$  (Chasles's axiom)
- 5. There are points A, B, C such that  $S_{ABC} \neq 0$  (dimension; not all points are collinear)
- 6.  $S_{ABC} = S_{DBC} + S_{ADC} + S_{ABD}$  (dimension; all points are in the same plane)
- 7. For each element r of F, there exists a point P, such that  $S_{ABP} = 0$  and  $\overline{AP} = r\overline{AB}$  (construction of a point on the line)

8. If 
$$A \neq B$$
,  $S_{ABP} = 0$ ,  $\overline{AP} = r\overline{AB}$ ,  $S_{ABP'} = 0$  and  $\overline{AP'} = r\overline{AB}$ , then  $P = P'$  (unicity)

9. If 
$$PQ \parallel CD$$
 and  $\frac{\overline{PQ}}{\overline{CD}} = 1$  then  $DQ \parallel PC$  (parallelogram)

10. If 
$$S_{PAC} \neq 0$$
 and  $S_{ABC} = 0$  then  $\frac{\overline{AB}}{\overline{AC}} = \frac{S_{PAB}}{S_{PAC}}$  (proportions)

- 11. If  $C \neq D$  and  $AB \perp CD$  and  $EF \perp CD$  then  $AB \parallel EF$
- 12. If  $A \neq B$  and  $AB \perp CD$  and  $AB \parallel EF$  then  $EF \perp CD$
- 13. If  $FA \perp BC$  and  $S_{FBC} = 0$  then  $4S_{ABC}^2 = \overline{AF}^2 \overline{BC}^2$  (area of a triangle)

Using this axiom system all the properties of the geometric quantities required by the area method were *formally verified* (within the *Coq* proof assistant [Tea09]), demonstrating the correctness of the system and eliminating all concerns about provability of the lemmas [Nar09].



# Full Angle Method/Solid Geometry

Full Angle Method Full Angle is defined as an ordered pair of line which satisfies the following rules (...) [CGZ96a].

Solid Geometry Method For any points A, B, C and D in the space, the signed volume  $V_{ABCD}$  of the tetrahedron ABCD is a real number which satisfies the following properties (...) [CGZ95].



# Coherent Logic GATP

Coherent Logic is a fragment of first-order logic with formulae of the following form:

$$A_1(x) \land \ldots \land A_n(x) \to \exists_{y_1} B(x, y_1) \lor \ldots \lor \exists_{y_m} B(x, y_m)$$

with a breath-first proof procedure sound and complete [BC05]. ArgoCLP (Coherent Logic Prover of the Argo  $Group^2$ )

- new proof procedures;
- proof trace exportable to:
  - a proof object in Isabelle/Isar;
  - human readable (English/LATEX).

not aimed at proving complex geometry theorems but rather at proving foundational theorems (close to the axiom level) [SPJ10].



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<sup>2</sup>http://argo.matf.bg.ac.rs/

Finding locus equation

# Finding locus equations<sup>3</sup>

For most DGS a locus is basically a set of points in the screen with no algebraic information.

- Numerical approach, based on interpolation (Cinderella, Cabri) [Bot02].
- Symbolic method, finding the equation of a locus [BL02, BA12].

Determine the equation of a locus set using remote computations on a server [EBA10].



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<sup>3</sup> [BAE07, BA12]

Finding locus equation

# Loci Finding — Algorithm

A statement is considered where the conclusion does not follow from the hypotheses.

Symbolic coordinates are assigned to the points of the construction (where every free point gets two new free variables  $u_i$ ,  $u_{i+1}$ , and every bounded point gets up to two new dependent variables  $x_j$ ,  $x_{j+1}$ ) so the hypotheses and thesis are rewritten as polynomials  $h_1, \ldots, h_n$  and tin  $\mathbb{Q}[u, x]$ .

Eliminating the dependent variables in the ideal (*hypotheses*, *thesis*), the vanishing of every element in the elimination ideal (*hypotheses*, *thesis*)  $\cap \mathbb{Q}[u]$  is a necessary condition for the statement to hold.



Finding locus equation

#### Locus Finding — Implementation

#### A Sage worksheet integrating GeoGebra





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Finding locus equation

# Implementation (cont.)

Two different tasks are performed over GeoGebra constructions:

- the computation of the equation of a geometric locus in the case of a locus construction;
- the study of the truth of a general geometric statement included in the GeoGebra construction as a Boolean variable.

Both tasks are implemented using algebraic automatic deduction techniques based on Gröbner bases computations.

The algorithm, based on a recent work on the Gröbner cover of parametric systems, identifies degenerate components and extraneous adherence points in loci, both natural byproducts of general polynomial algebraic methods [BA12].



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# Integration — DGSs & GATPs

- GCLC/WinGCLC A DGS tool that integrates three GATPS: Area Method, Wu's Method and Gröbner Bases Method [Pre08, JQ06, Jan06].
- Theorema Project Theorema is a project that aims at supporting the entire process of mathematical theory exploration within one coherent logic and software system [BCJ<sup>+</sup>06]. Implementation of the Area Method Method[Rob02, Rob07].
- JGEX is a software which combines a DGS and some GATPs (full angle, Wu's Method, Deductive Databases for the full angle) [YCG10a, YCG10b, CGY04].
- GeoProof DGS tool that integrates three GATPs Area Method, Wu's Method and Gröbner Bases Method [Nar07a].

Others: The Geometry Tutor, Mentoniezh, Defi, Chypre, Cabri-Euclide, Geometrix, Baghera, MMP-Geometer, Geometry Explorer, Cigderella.



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# Integration/eLearning (DGSs & GATPs & RGPs)

Modular approach: I2G & I2GATP formats.

WebGeometryLab: a Web environment incorporating a DGS (GATPs) and a repository of geometric problems, that can be used in a synchronous and asynchronous fashion and with some adaptative and collaborative features [QJ06b, SQ08, SQ10, SQ12].

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## Repositories of Geometric Problems

GeoThms — a Web-based framework for exploring geometrical knowledge that integrates Dynamic Geometry Software (DGS), Automatic Theorem Provers (ATP), and a repository of geometrical constructions, figures and proofs. [JQ06, QJ07].

TGTP — a Web-based library of problems in geometry to support the testing and evaluation of geometric automated theorem proving (GATP) systems [Qua11].



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# TGTP<sup>4</sup>

A comprehensive and easily accessible, library of GATP test problems.

- Web-based, easily available to the research community. Easy to use.
- Tries to cover the different forms of automated proving in geometry, e.g. synthetic proofs and algebraic proofs.
- provides a mechanism for adding new problems.
- ► (...)

It is independent of any particular GATP system  $\mapsto$  the I2GATP common format, an extension of the I2G format [SHK<sup>+</sup>10] to accommodate the geometric conjectures [Qua12, WSA<sup>+</sup>12].



## What to Do?

Integration of Methods integrate the study of logical, combinatorial, algebraic, numeric and graphical algorithms with heuristics, knowledge bases and reasoning mechanisms.

System Construction design and implement integrated systems for computer geometry, integrating, in a modular fashion, DGSs, ITPs, GATPs, RGPs, etc. in research and/or educational environments.

Higher Geometry The existing algorithms should be extended and improved, new and advanced algorithms be developed to deal with reasoning in different geometric theories.

Axiom Systems Development of new axiom systems, motivated by machine formalisation. [ADMAv]

Formalisation formalising geometric theories and methods.



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