# Topics in Automated Theorem Proving 

Course (236714, 2013/14)

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## Lecture 4 (November 7, 2013)

## Ground clauses

- A ground literal is an atomic or negated atomic formula with constant terms and no free variables.
- A ground clause is a clause consisting of ground literals. and no free variables.

We have reduced satisfiability of first order logic to satisfiability of propositional logic.

## Monadic First Order Logic

Let us look at the case of first order logic with the following restrictions:

- We have only unary relation symbols.
- We have no equality.
- We do allow equality.

We discuss Skolem normal form.
Homework: Show that in this case satisfiability is decidable.
Theorem: If we have only one binary relation symbol and equality, satisfiability is not decidable.
E. Börger and E. Grädel and Y. Gurevich,

The Classical Decision Problem, Springer-Verlag, 1997

Avoiding too many terms, I

Now look at a formula

$$
\Phi=\forall \bar{x} \exists \bar{y}[\phi(\bar{x}) \wedge \psi(\bar{y})]
$$

where $\phi, \psi$ are quantifierfree.
This is equivalent to

$$
\psi=\forall \bar{x}[\phi(\bar{x}) \wedge \exists \bar{y} \psi(\bar{y})]
$$

- Skolemizing $\Phi$ produces several functions, hence infinitely many terms.
- Skolemizing $\Psi$ produces only constant symbols, hence finitely many terms.

Conclusion: Putting first into prenex normal form and then introducing Skolem functions is not always preferable. Homework: Discuss strategies to safe terms when Skolemizing.

## Avoiding too many terms, II

We do not want to instantiate all clauses with all the terms!

- Assume we have

$$
S_{1}(y) \vee R(x) \text { and } S_{2}(x) \vee \neg R\left(y^{2}\right)
$$

- Substituting for $y$ the term $u^{2}$ and for $x$ the term $u^{4}$ we get

$$
S_{1}\left(u^{2}\right) \vee R\left(u^{4}\right) \text { and } S_{2}\left(u^{4}\right) \vee \neg R\left(u^{4}\right)
$$

- Resolution gives

$$
S_{1}\left(u^{2}\right) \vee S_{2}\left(u^{4}\right)
$$

- Similarly
gives

$$
\begin{gathered}
S_{1}(y) \vee R(x) \vee R\left(y^{2}\right) \\
S_{1}\left(u^{2}\right) \vee R\left(u^{4}\right) \vee R\left(u^{4}\right) \\
S_{1}\left(u^{2}\right) \vee R\left(u^{4}\right)
\end{gathered}
$$

Handling substitutions

There is theory behind this!

## Unification theory



John Alan Robinson, 1928 *
John Alan Robinson, A Machine-Oriented Logic Based on the Resolution Principle, Journal of the ACM, vol 12, 2341, 1965.

See Lecture 4

## Unification (according to Wikipedia)

- (link to wikipedia)
- (relative)

The deduction rules

Let $\operatorname{Term}(\tau)$ be the set of terms over the vocabulary $\tau$. Let $\sigma$ be a substitution, a function from the variables Var $\rightarrow \operatorname{Term}(\tau)$.
Let $C\left(x_{1}, \ldots, x_{n}\right), D\left(x_{1}, \ldots, x_{n}\right)$ be clauses with free variable $\bar{x}$ and $L\left(x_{1}, \ldots, x_{n}\right)$ be a literal.

We have two deduction rules:

## Factoring

$$
\frac{C\left(x_{1}, \ldots, x_{n}\right)}{C\left(\sigma\left(x_{1}\right), \ldots, \sigma\left(x_{n}\right)\right)}
$$

Resolution

$$
\frac{C\left(x_{1}, \ldots, x_{n}\right) \vee L\left(x_{1}, \ldots, x_{n}\right), D\left(x_{1}, \ldots, x_{n}\right) \vee \neg L\left(x_{1}, \ldots, x_{n}\right)}{C\left(\sigma\left(x_{1}\right), \ldots, \sigma\left(x_{n}\right) \vee D\left(\sigma\left(x_{1}\right), \ldots, \sigma\left(x_{n}\right)\right)\right.}
$$

## Soundness

- Factorization is a special case of the rule

$$
\frac{\forall \bar{x} \phi(\bar{x})}{\phi(\bar{t})}
$$

where $\bar{t}$ is a sequence of terms.
In human language: If all $x$ are Human, so Socrates is a Human.

- Resolution combines the above with propositional resolution.


## Completeness

We use Herbrand's Theorem.
Let $\Sigma$ be a set of $\operatorname{FOL}(\tau)$ and $\Sigma_{s k}$ its Skolem Normal Form.

- Applying Factoring we can generate all ground clauses.
- Applying resolution we can check satsifiability.

Problem: How to choose the right substitutions efficiently?

The unification problem.

The problem we are facing now:
Given two sequences terms
$t_{1}(\bar{x}), \ldots, t_{n}(\bar{x})$ and $u_{1}(\bar{x}), \ldots, u_{n}(\bar{x})$

- does there exist a substitution $\sigma$ such that for all $i \leq n$

$$
t_{i}(\sigma(\bar{x}))=u_{i}(\sigma(\bar{x}))
$$

as terms.

- If yes, how can we find it, of no, how can we be sure?

A substitution $\sigma$ with the above properties is called a unifier for $t_{1}(\bar{x}), \ldots, t_{n}(\bar{x})$ and $u_{1}(\bar{x}), \ldots, u_{n}(\bar{x})$.

Note: It is enough to solve the unification for pairs of terms $t(\bar{x})$ and $u(\bar{x})$.

## Comparing unifiers

Let $\sigma_{1}, \sigma_{2}$ be two unifiers for $t$ and $u$.

- $\sigma_{1}$ is more general than $\sigma_{2}$ if the is a substitution $\rho$ such that

$$
\rho \circ \sigma_{1}=\sigma_{2}
$$

- $\sigma_{1}$ is a most general unifier, of for every other unifier $\sigma_{2}$ there exists a substitution $\rho$ such that

$$
\rho \circ \sigma_{1}=\sigma_{2}
$$

Proposition: If $\sigma$ is a most general unifier for $t$ and $u$, then it is unique up to renaming variables.

Lecture 5, November 14, 2013

- To be written


## Tirgul 5, November 21, 2013

- We complete the QE for equality only.
- The following formulas are logically equivalent:

$$
\exists x(\phi(x) \wedge x=y) \text { and }\left.\phi(x)\right|_{y} ^{x}
$$

where $\left.\phi(x)\right|_{y} ^{x}$ is the result of substituting $y$ for $x$ in $\phi$.

## Proof:

Use the definition of the meaning function for $\exists$ and the definition of substitution.

Lecture 6, November 21, 2013

Fourier-Dines-Motzkin Procedure

Fourier 1826, Dines 1918, Motzkin 1936

- The structure: $\mathcal{R}_{+}=\langle\mathbb{R},+, \leq, 0,1\rangle$
- The Theorem: $\mathcal{R}_{+}$allows QE .
- Some history


Jean Baptiste Joseph Fourier (1768-1830)


Lloyd L. Dines
(1885-1964)


Theodore Samuel Motzkin (1908-1970)

- Wikipedia on Jean Baptiste Joseph Fourier, (web), (relative),

ON LINEAR
INEQUALITIES

L.L. Dines and N.H. McCoy, On Linear Inequalities, Trans Royal Soc Canada (1933)
- Obituary of Theodore Motzkin, (web), (relative),

Terms and atomic formulas for $\mathcal{R}_{+}$.

Atomic Terms: Variables $x_{i}$, constants 0,1 ,
Constant Terms: Using commutativity, associativity and $(x+0)=x$, we can reduce every constant term to

$$
(n)=\underbrace{1+1+\ldots+1}_{n}
$$

We write $\mathbf{n} \cdot t$ for $(\underbrace{t+t+\ldots+t}_{n})$.
Terms: If $s, s_{i}, t, t_{i}(i \in \mathbb{N})$ are terms, so are
$(s=t), \sum_{i=0}^{k} \mathbf{n}_{i} t_{i}$
Atomic Formulas: $t_{1} \approx t_{2}, t_{1} \leq t_{2}, \mathbf{n} t_{1} \approx \mathbf{m} t_{2}$

$$
\sum_{i=0}^{k} \mathbf{n}_{i} t_{i} \approx \sum_{j=0}^{\ell} \mathbf{m}_{j} s_{j}
$$

## Normal form for quantifier-free formulas

- Every term $t\left(x_{1}, \ldots, x_{n}\right)$ can be writen as

$$
t=\mathbf{n}_{1} \cdot x_{1}+\mathbf{m}_{1}+\sum_{i=2}^{n} \mathbf{m}_{i} \cdot x_{i}=\mathbf{n}_{1} \cdot x_{1}+s\left(x_{2}, \ldots, x_{n}\right)
$$

where $x_{1}$ does not occur in $s$.

- We introduce a new function symbol $\operatorname{minus}(t)=-t$ with the rules
$-t+t=t+(-t)=0,-(-t)=t$ and $-(s+t)=(-s)+(-t)$. and binary relation symbols $\{<,=,>, \geq\}$ with the obvious interpretations.
- Using minus $(t)=-t$ we now can show that every atomic formula is equivalent to a formula of the form

$$
x \Delta t(\bar{y}) \text { or } s(\bar{y}) \Delta x
$$

where $\Delta \in\{\leq,<,=,>\geq\}$.

- Conversely, every atomic formula $A\left(x_{1}, \ldots, x_{n}\right)$ in which minus is used is equivalent to an atomic formula $B\left(x_{1}, \ldots, x_{n}\right)$ in which minus is not used.
- Similarily, the symbols $\{<,=,>\geq\}$ can be eliminated from quantifier-free formulas without introducing quantifiers.

To be done by induction!

The theory $\operatorname{Th}\left(\mathfrak{R}_{+}\right)$admits effective QE and hence is complete.
Fourier 1826, Dines 1918, Motzkin 1936

It is enough to prove it for formulas of the form

$$
\exists x\left(\bigwedge_{i} t_{i}(\bar{y}) \Delta_{i} x \wedge \bigwedge_{j} x \Delta_{j} t_{j}^{\prime}(\bar{y}) \wedge \bigwedge_{k} s_{k}(\bar{y}) \Delta_{k} 0\right)
$$

Where $\Delta_{i}, \Delta_{j} \in\{\leq,<\}$.
This is equivalent to

$$
\exists x\left(\bigwedge_{i} t_{i}(y) \Delta_{i} x \wedge \bigwedge_{j} x \Delta_{j} t_{j}^{\prime}(\bar{y})\right) \wedge\left(\bigwedge_{j} s_{j}(\bar{y}) \Delta_{j} 0\right)
$$

## Proof continued

But

$$
\exists x\left(\bigwedge_{i} t_{i}(y) \Delta_{i} x \wedge \bigwedge_{j} x \Delta_{j} t_{j}^{\prime}(\bar{y})\right)
$$

is equivalent to

$$
\bigwedge_{i, j} t_{i}(\bar{y}) \Delta_{i, j} t_{j}^{\prime}(\bar{y})
$$

where

$$
\Delta_{i, j}= \begin{cases}\leq & \text { if both } \Delta_{i}=\Delta_{j}=\leq \\ < & \text { if } \Delta_{i}=<\text { or } \Delta_{j}=<\end{cases}
$$

Q.E.D.

The structure $\mathcal{Z}_{+}=\langle\mathbb{Z},+, \leq, 0,1\rangle$, Presburger Arithmetic.

- Can we have QE also in this case?
- We can add unary relation symbols $D_{m}(x)$ with the interpretation $x$ is divisible by $m$.
- Theorem:(M. Presburger) $\left.\mathcal{Z}_{+}=\angle \mathbb{Z},+, \leq, D_{m}(x), 0,1\right\rangle$ for $m \in \mathbb{N}$ has QE ,


$$
\mathcal{Z}_{+}=\langle\mathbb{Z},+, \leq, 0,1\rangle \text { has no } \mathrm{QE}
$$

- Let $A \subset \mathbb{Z} . A$ is a ray, if $A$ is finite or there is $a \in \mathbb{Z}$ with $A=A_{+}(a)=$ $\{b \in \mathbb{Z}: b \geq a\}$ or $A=A_{-}(a)=\{b \in \mathbb{Z}: b \leq a\}$.
- Every quantifier-free definable set over $\mathcal{Z}_{+}$is a ray.

Use induction!

- $\exists x(x+x=y)$ defines a set which is not a ray.

It defines the even numbers.

The real numbers

$$
\mathcal{R}_{\text {field }}=\langle\mathbb{R},+, \times, 0,1\rangle \text { and } \mathcal{R}_{\text {ofield }}=\langle\mathbb{R},+, \times, \leq 0,1\rangle
$$

Theorem:(A. Tarski)

- $\mathcal{R}_{\text {ofield }}$ has EQ.
- $\mathcal{R}_{\text {field }}$ does not have EQ. We showed this already.


Alfred Tarski-Teitelbaum (1901 - 1983) (web), (relative),

## Examples for QE over the reals

- Solvability of polynomial equations: $\exists x \sum_{i=0}^{k} a_{i} x_{i}=0$.
$k$ odd and $a_{k} \neq 0$ this is always true.
$k$ even and $a_{k} \neq 0$ this may be difficult......
- More sophistigated examples may be found in:
D. Lazard

Quantifier elimination: Optimal solutions for two classical examples, Journal of Symbolic Computation, vol. 5 (1988) pp. 261-266.

