

# Application of **Synchronization Coverage**

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PPoPP 2005

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on Advanced Topics in Concurrent  
Programming (236802) by  
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# Outline

- Testing and Coverage
- Synchronization coverage
- Use Cases
- Back to the Future

# Testing

- Testing usually takes 40%-80% of the development time.
- Bug detection rate drops as the code improves.
- How good are the tests? Can the client quantify the quality of the tests?
- When should testing cease?
  - Testing for regression suits must be brief and to the point
- Where should testers focus efforts?

# Coverage

- What is coverage?
  - For a given system, define a set of **testing tasks**.
  - For each task, check if it was actually performed (**covered**) in some test(s).
  - Measure the **fraction** of tasks performed.
- Coverage is the main means for
  - **Quantifying** testing quality (contracts, company policies)
  - Targeting **future test** creation
  - Guiding **code review**

# Sequential Coverage Models

## Hit Parade

- Some coverage models are **very popular**:
  - **Statement** – each code line is a task. DA requires 100% statement coverage.
  - **Branch-point** – each decision outcome (e.g., the two branches of “if”) is a task
- Others are **less popular**:
  - **Multi-condition** – combinations of decision outcomes form single task
- Yet others are **rarely used**:
  - **Define-use** – each pair of data definition and use is a task
  - **Mutation** – the extent to which tests can discriminate the code from slight mutations. Errors are seeded in the code. Discovering each error is a task. The fraction of discovered seeded errors is an indication for the number of real bugs still left in the code.
  - **Path** – a possible flow of the code from entry point to exit point is a task.
- **Why?**

# A coverage model will be widely accepted if...

- ✓ Tasks are **statically generated** from the code.
  - *Coverage percentage* can be measured.
- ✓ Each task is **well-understood** by the user.
  - True for most models, but not all.
- ✓ Almost all tasks are **coverable**;
  - for the few tasks that are not, the programmer can tell why.
  - True for statement coverage, but not for define-use, mutation, multi-condition.
  - Otherwise, the tester wastes time investigating.
- ✓ Each uncovered task yields an **action item** (Either redundant code or missing tests).

# Coverage for Concurrency

- ◆ Concurrent programs are bug-prone and concurrent testing is hard.
- ◆ A combination of sequential and concurrent coverage is required to verify testing adequacy (Factor et al.).
- ◆ 100% statement coverage is far from guaranteeing thorough testing:
  - ◆ Good programmers try to make synchronized code parts small.
  - ◆ On a single processor, it means a low probability for a thread to lose the processor while still in the synchronized code.
  - ◆ In 2005, threads were often used on a single core.
  - ◆ Removing all synchronization commands from a concurrent code, and testing until full statement coverage was reached often resulted in hardly discovering any bugs.

# Coverage for Concurrency

Good concurrent coverage is called for

No concurrent  
cov. model  
meets  
requirements

No concurrent cov. Model is widely used

# 1. Concurrent Pair of Events

- A task is a pair of code lines which were consecutively executed in a test, with an additional field:
  - “False” if they were executed by the same thread
  - “True” otherwise
- Too many tasks – full coverage is hard
- Which tasks are coverable?
- Used for evaluating testing progress



# Synchronization Coverage!

- A task is a synchronization primitive in the code which does something “**interesting**”.
- synchronized blocks in Java:

```
synchronized(lock1) {  
    counter++;  
    updateDB();  
}
```

```
synchronized(lock1) {  
    counter--;  
    updateDB();  
}
```

- Two tasks for each synchronized block:

- **blocked**: A thread waited there, because another thread held the lock.

- **blocking**: A thread holding the lock there caused another thread to wait.

- To cover the code:

- Create a list of synchronization code areas
- List tasks for each code area
- Full coverage is when all tasks were tested for all sync. code areas

# Example: Java synchronized blocks tasks

  
`synchronized(lock1) {`  
`synchronized(lock1) {`  
`counter++;`  
`updateDB();`  
`}`

blocking

blocked

  
`synchronized(lock1) {`  
`synchronized(lock1) {`  
  
`counter--;`  
`updateDB();`  
`}`

blocking

blocked

# Other Tasks: Try Lock

- Task “Failed”
- Task “Succeeded”
- If a task never happens: Insufficient testing or a redundant sync operation

# Other Tasks: Wait (on a condition)

- Task “Repeated” (wait was called at least twice in the same block, in the same run, by the same thread)
- Wait proper use is in a loop
- Bug pattern: calling wait and not verifying the condition still holds upon wake-up.
  - Wake-up may happen spuriously in some systems
  - Another thread may have invalidated the condition between notification and wake-up

# Other Tasks - Future Work:

- Semaphore – Wait:
  - Task “Blocked” (semaphore was not immediately available), task “Non-Blocked”
- Semaphore –Try Wait:
  - Task “Succeeded” , task “Failed”
- Notify (NotifyAll, Signal, signalAll, Broadcast):
  - Task “Had Target”, task “Had no Target”
  - “Lost Notify” bug pattern: wait called after notify, notify had no target, program hangs
  - Testing for “had no target” may be hard, but usually possible. Requires deep understanding.

# Other Tasks – Bad Ideas:

- Task “interrupted” for Wait:
  - Usually uncoverable

# Synchronization coverage

## Meets the requirements:

- ✓ Tasks are generated statically from the code.
- ✓ Each task must be well-understood by the developer/tester:
  - Less trivial than for statement coverage, but not too difficult for a reasonable concurrent programmer.
- ✓ Each task must be coverable:
  - A synchronized block is written in order to make threads wait. If it can't happen, perhaps it's redundant.
  - Sometimes it's not easy to make a concurrent task happen, but this is **precisely the purpose**: make an effort to make the concurrent test thorough.

# and...

- ✓ Each uncovered task yields an action item:
  - If the synchronization is redundant, remove it.
    - Otherwise, some interleaving scenario has not been tested. Strengthen the test.
  
- ☹ Few tasks genuinely cannot be covered.
  - Peculiarities of the synchronization protocol.

# Uncoverable synchronization tasks

```
public static void main (String args) {  
    ...  
    synchronized (lock) {  
        new Thread(...).start();  
        ...  
    }  
}
```

- ☹️ If thread..start() waits for lock, it will always be blocked, main will always be blocking.
- ☹️ This is rare; such tasks can individually be identified when reviewing the uncovered tasks.
- ☹️ (Same for statement coverage.)

# Implementation: ConTest

- IBM tool: **ConTest** (concurrent testing tool).
- Implemented for Java and for C/Pthread.
  - The code is instrumented, and a list of the tasks is computed.
  - In test runtime, it keeps a representation of the synchronization objects, e.g., in order to know when a lock is held.
  - **Noise injection mechanisms** (yields and sleeps) help obtaining the tasks.
- The concept can be adopted for any set of synchronization primitives (Windows, Java 5.0 new concurrency library).
  - Task definition for each primitive depends on primitive semantics.

# Field pilot #1: Unit-test of a real-life concurrent protocol

- VOD system.
  - Heavy stream operations by some threads
  - Business logic by other threads, with real time interleaving
  - Business logic is an inner class of the Thread Manager class, written from scratch
  - 160 classes
- A synchronization protocol (Thread Manager) was isolated and abstracted.
  - \_ Tester class implemented
  - \_ Heavy functions replaced by random choices or constant results (must be done with protocol understanding!)
  - \_ **Several bugs fixed using various other methods.**
- Tested with ConTest.
  - 100% sync. coverage reached after less than 1 hour.
  - This gives confidence in the quality of the protocol.
  - Without noise injection, most of the tasks would not have been performed.
  - **No additional bugs found.**

# Field pilot #2: synchronization coverage to guide review

- A system to identify complex events in distributed context, and give warnings.
  - For example, warn that many resources are near their limit.
- Synchronization coverage – initially 25%.
  - 575 classes , 16 with sync primitives (not too many, but a lot to review)
  - Can the number of sync files be less?
  - 9 classes with 3 or less sync primitives
  - 4 1-sync-primitive-files: 2 different code base, 1 sync not needed
- One-hour review of uncovered tasks quickly revealed –
  - 2 tasks in dead code.
  - 2 unnecessary synchronizations.
  - 4 tasks : missing tests.
  - 1 task hard-to-test – carefully review.
  - 1 task: missing the application code (missed due to abstraction)
  - Few bugs
- Measurement #2: 39%. Slides by Y. Nir-Buchbinder, adapted by O. Agmon Ben-Yehuda

# What happened

Since 2005?

# ConTest

- ConTest is an active product and service of IBM. A 10-class version is available for free, a larger version is a commercial product.
- <http://www.alphaworks.ibm.com/tech/contest>
- ConTest now checks if locks are taken in a reverse order, thus possibly leading to a deadlock (source: conversation with Shmuel Ur).
- Chess

# Citations (June 2011)

- According to ACM: 18 citations
- 6 self
- 5 by Yuanyuan (YY) Zhou
- For example:

# SyncFinder (OSDI 2010)

- Ad hoc synchronization considered harmful (incurs about 50% chance of bugs, hard to review)
- SyncFinder finds ad-hoc sync points, thus enabling tools like ConTest to work on them.
- But do not use them!

# CTrigger (ASPLoS 2009)

- Exposing atomicity bugs in real software (Apache, MySQL, Mozilla)
- 2-4 orders of magnitude faster than stress testing.
- Fast bug reproducibility without the limitation of a single thread at a time.
- Focuses on unrealizable interleavings, deliberately inducing the rare interleavings.

# Kim, Cho, Moon 2011

- Re-implemented Sync. Coverage using a deterministic technique.
- 1.5-144 times faster than a random approach, with no abstraction.
- Only checked simple codes (fft, lu-decompose, basic compression, etc.)

# Conclusion

- A good concurrent coverage model, and a supporting tool, were strongly needed.
- Synchronization coverage met this need.
- In 2005, the authors had reasons, both theoretical and practical, to believe that it can be widely used in the industry.
- In 2011 we can see that the authors prediction came to pass, on the basis of publications and available tools.

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